AX Series

Programmable Controller







invt

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Industrial Automation: Servo & Motion Control Frequency AC Drive • HMI Electric Power: SVG New Energy Vehicle Electric Control System

 Intelligent Elevator Contral System Solar Pump Controller UPS

 Motor & Electric Spindle Traction Drive

Online Energy Management System

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PLC







CONTENTS >>

Making collaboration between human and machine more *simple* and *effective*

EtherCAT open network

Advanced motion control

Large-scale distributed I/O

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6



AX series programmable controllers

Product Features	3
Technical Data	13
Main Dimensions	16
Ordering Data	17
Automation Product Family	19
Marketing Service Network	20

Product Features

AX series programmable controllers are a family of INVT high-performance general-purpose controllers for medium and large control systems. With advanced embedded functions and rich scalability, the product can provide best automated control systems by integrating with diversified motion control communication buses and connecting to drive devices, so as to improve production efficiency and quality, and reduce development and maintenance costs.

High-speed calculation capability >>

Uses the CPU with the basic command processing speed up to 1ns.



Large-scale distributed expansion >>

Supports EtherCAT distributed expansion.



Advanced motion control >>

Integrated with rich motion control functions; Implements synchronization control and advanced motion control such as electronic cam, electronic gear, and positioning by using high-speed EtherCAT bus or pulses.

Electronic cam/gear >>

Processing quintic polynomial cam curve tracks

Obtains continuous trajectories and smooth motion trajectories by specifying the speed, position and acceleration boundary conditions.



Cam curves online modifying

No need to regenerate cam curves, since position compensation can be made for motion track points with deviations.



Real- and virtual-axis control mode

Uses virtual axes to simplify mechanical structure, improve accuracy and response speed, and achieve the linkage, collaboration, and coherence of multi-axis motion.





Flying shear

Achieves fixed- and variable-length cutting on materials by tracking feeding speed, setting cutting lengths or tracking color mark positions, and automatically planning movement trajectory.



Chasing shear

Achieves synchronous cutting and quick return by setting the starting points and lengths of synchronization zones, determining the allowable traverse ranges of the shearing axis and the starting and end points of reciprocating motion, and planning cam track curves.



Color mark detection

Obtains the actual servo motor position by receiving mark signal; and achieves fixed-position cutting on materials by compensating for the cutter axis offset during position obtaining.





Supports 200k pulses/s, including pulses with direction, forward/reverse pulses and quadrature pulses, to implement position and speed control.

Single axis control

Includes manual, jog, homing, PTP and speed control modes.



Multi-axes interpolation

Allows axes 2, 3, and 4 to execute simultaneous linear motion; and supports running at relative and absolute positions.



Arc interpolation

Supports arc interpolation for any two axes on planes XY/XZ/YZ using the trigonometric function interpolation method; and supports multi-axis linear interpolation with trajectory distortion controlled within 0.001mm.



Diverse ACC/DEC processing

Pre ACC/DEC control on T- and S-type curves



to the at at at at at at at at

Visual configuration >>

Graphical configuration interface

Configuration programming

- Supports the programming language system compliant with C61131-3 standards.
- Supports the six programming languages compliant with PLCopen standards.
- Supports programming methods including programs, functions, and function blocks, reducing programming time.
- Easy to achieve complex motion control for the use of high-level programming languages.



Highly effective debugging

- Uses the LAN or USB interface to perform online debugging and offline simulation.
- Online debugging: Online program modifying and single-step running, improving debugging efficiency.
- Offline simulation: In case of no servo axis connection, virtual axes are added to perform simulated debugging on programs, making debugging flexible.



Safe and easy to use >>

Compatible with thermal resistors and thermocouples

- The temperature module supports both thermal resistors and thermocouples.
- Supports 4-wired thermal resistors without external power supply.

Permanent storage of data

At power failure, data is automatically saved to the FLASH memory, without the use of a backup battery.



PLC program zo Power-failure protect

Security

- Multi-level security password and user permission management.
- Encrypted communication between the development system and controller, protecting automation equipment with data exchange from unauthorized access.
- Disabled program upload function which is use d to protect users' intellectual property rights.









	At controller power-off
one	Permanently saved
tion zone	Permanently saved



Preventive maintenance

Collects data and monitors status through INVT IoT platform to predict possible failure events before failure occurs.



Event record

Saves various event records such as program writing, errors, and power failures, helping quick fault locating.

Bitth	C unc adve					
	0 : 188 MIN		- 881	 	1.016	XIE
78	0490	10		411		
•	Int 12-2018 09-31-41	CODESI:15 Carerol ready		(DH		
•	MR 12-2010-09-31-41	Application (Application) started		(Deplep-		- 11
	Add 12,2018 00:31-41	01,047,0044		DIPR.4		
	48.12.2018 09:31-41	OK DET COMM		Depricity_	1882	
•	48.12.2018 09:31-41	ON_INIT_TARKS		CHIPR. 9		
0	08.12.2018 09.31.41	CH_MET_THREE		Owned.	1442	
	08-12-2018 09:31-41	Bootpropert of application [Application] loaded		Creaker		
	08-12-2018-09-31-41	to return area in biographic of application (Application)		Creater		
	08.12.2018 09:31-41	Event received: Application - Application > Insded		NO-CEN.	1441	
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	08.12.2018 09:31-41	Event received: Application «Application» loaded		80-440.	0.0.1	
	18.02.2018 (9):71-41	Event received: Application (Application) Insted		Sill-Terps	aber_10.0.1	
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	08.12.20.01 09:31-40	Setting router 0 address to (5008)		Crokuter		
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	08.12.22.08.09.21-45	01 2473		ONPICE	1882	
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0	08.12.2018 09.31-40	Local network address: 172.18.187.8		Deellov?		
1						202

Backend diagnosis

Provides a shortcut to diagnosis, enabling users to check equipment status easily.

24 14 15 26 16 16 16 17 1 24 17 16 16 16 16 16 16 17 1	10-316119	
• • • • • • • • • • • • • • • • • • •	0 10 3 1000 84.00 05 10 10 10 10 10 10 10 10 10 10 10 10 10	

Multilanguage

Free switchover between Chinese, English, and Japanese.



Modular structure without backplane

Modular design, compact size, and flexible expansion, reducing configuration space



Snap-in installation and detachable terminal blocks, implementing quick installation







EtherCAT bus

- The CPU module supports 32 servo axes. Supports the expansion up to 125 slave
- EtherCAT modules.
- Supports the simultaneous expansion of both servo axis and racks.
- Fieldbus communication rate up to 100Mbps, with the max. distance between two nodes up to 100m. AX70



RS485 serial interface

- Two-channel independent serial interface. Supports Modbus RTU master/slave station.
- Supports the access from 31 slave devices
- when serving as the Modbus RTU primary node.



USB and SD card slots

- Mini USB interface, supporting program update and online debugging.
- Supports 32GB Micro SD card for data recording and program update.



LAN interface

- Supports Modbus TCP slave station.
- Supports the simultaneous communication with 16 master stations when serving as a Modbus TCP slave station.
- Supports the access from 63 slave stations when serving as the Modbus TCP master station

PC





interrupted .



Local high-speed I/O

- 16 channels of high-speed input and 8 channels of high-speed output, supporting 4-axis pulse motion control.
- 8 channels of 200kHz single phase or AB phase high-speed pulse counting.
- 6 channels of differential or single end input.
- 8 channels can be externally high speed



Local bus

- Supports 16 digital I/O modules, with the refresh time from the beginning to the end less than 8ms.
- Supports 8 analog I/O modules, with the refresh time from the beginning to the end less than 8ms.



CPU module

Technical Data

Model		AX70-C-1608P	AX71-C-1608P	
Rated working voltage		DC24V(-5%~+5%)	DC24V(-5%~+5%)	
Memory				
Dreaman	Size	10M Word	10M Word	
Program capacity	Qty	POU definitions: 3000 POU instances: 6000	POU definitions: 3000 POU instances: 6000	
Data capacity		8M Word	8M Word	
Capacity of data save	ed at power failure	512K Byte	512K Byte	
Max capacity of expa	anded SD card	32G	32G	
1/O				
High-speed I/O		16 high-speed inputs and 8 high-speed outputs	16 high-speed inputs and 8 high-speed outputs	
Max. number of local	expansion modules	16	16	
Max. number of	Local	256	256	
I/O points	EtherCAT bus	32000	16000	
High-speed input		Supporting 8 channels of 200kHz single phase or A/B phase high-speed pulse counting, in which A/B phase supports frequency multiplication by 1, 2, and 4. Supporting 6 channels of differential input or single end input.	Supporting 8 channels of 200kHz single phase or A/B phase high-speed pulse counting, in which A/B phase supports frequency multiplication by 1, 2, and 4. Supporting 6 channels of differential input or single end input.	
High-speed output		8 channels of 200kHz high-speed output, supporting 4-axis pulse motion control.	8 channels of 200kHz high-speed output, supporting 4-axis pulse motion control.	
Support for I/O interru	ption	8 channels of high-speed interrupt input.	8 channels of high-speed interrupt input.	
Interrupt response tim	ie	250us	250us	
Communication netw	ork and interface			
Ethernet		RJ45*1, 10/100Base-TX, supporting PLC software downloa	d, Modbus TCP, and TCP/IP protocols	
EtherCAT		RJ45*1, 100Base-TX, with the distance between two slave	nodes less than 100m	
CANopen		DB9F*1 (COM2, sharing the interface with RS485)		
Serial communication	(RS485)	DB9F*2, supporting Modbus RTU primary and secondary r	iodes	
USB Mini USB*1, for PC communication, program download and debugging			l debugging	
Storage card Micro SD*1, for system update				
Inter-PLC connection Ethernet/Modbus RTU				
Upper computer conr	nection	Ethernet/Modbus/CANopen		
Modem connection Supported				
Command period				
Execution time on bits	3	1ns		
Execution time on words		4ns		
Execution time on fixed-point numbers		80ns		
Execution time on floating-point numbers		150ns		
Motion control				
Number of control axes	Max. number of control axes	32	8	
	Manual functions	•	•	
	Homing	•	•	
	Point locating	•	•	
	Speed control	•	•	
	Speed variation (reserved)	•	•	
	Emergency stop	•	•	
	Halt (reserved)		•	
Point-to-point	Reset	•	•	
(FTF) motion	Position superposition	•	•	
	Magnification variation	•	•	
-	(reserved) Time and position control		•	
	(reserved)	-	-	
	Time and speed control (reserved)	•	•	
Interpolation motion	Linear interpolation	4 axes, 200kHz, in three modes: pulse + direction, FWD/REV pulse sequence, and quadrature encoder pulse	4 axes, 200kHz, in three modes: pulse + direction, FWD/REV pulse sequence, and quadrature encoder pulse	
	Plane arc interpolation	2 axes, 200kHz, in three modes: pulse + direction, FWD/REV pulse sequence, and quadrature encoder pulse	-	
	Multi-group linear interpolation (bus)	•	-	
Axis group (reserved)	Multi-group plane arc interpolation (bus)	•	-	
	Single- and multi-axis hybrid control (bus)	•	-	

	Max. number of e-cam tables	64	
Electronic cam (e-cam)	Max. point number in all e-cam tables	4194240	
	Max. point number in one e-cam table	65535	
	TP compensation	64 groups	
Electronic gear (e-ge	ar)	•	
Motion control period		EtherCAT data communication is period; 1ms of pulse communicat	
Position unit		Pulses, millimeter (mm), inch (in.)	
Clock			
Internal clock		At environment temperature of 55 At environment temperature of 25 At environment temperature of 00	
Configuration progra	Imming		
Programming platform		Invtmatic Studio	
Programming lang	uages	IL、ST、FBD、LD、CFC、SF	
Basic specifications			
Running environme	ent temperature	-10~55°C	
Running environment humidity		10%–95% (no condensation)	
Storage temperature		-40~70 C	
Storage environment humidity		10%–100%, with condensation	
Ingress protection rating		IP20	
Running environme	ent	No corrosive gas	
Altitude		2000m or lower	
Installation manner		In control cabinet	
Pollution degree		Degree 2 or lower, compliant with	
Surge		2kV	
Anti-interference		2kV voltage-withstand power cab	
ESD class		6kV CD or 8kV AD	
Vibration resistant		5–8.5Hz, vibration amplitude of 3.	
Dimensions and weight	ght		
W x H x D (mm)		80*90*95mm	
Weight		0.38kg	

Power supply module

Model	AX-PWR
Input power exception	AC100~240V(-15%~+10%)
Input frequency	50/60Hz(-5%~+5%)
Output voltage	DC24V(-5%~+5%)
Rated output current	2A
Efficiency	>70%
Overcurrent protection	Supported
Fuse	Built in
Dimensions (W x H x D)	32x90x117mm

Note: The symbol • indicates supported; the symbol-ndicates not supported.



	64
	4194240
	65535
	64 groups
the same in control	EtherCAT data communication is the same in control period: 1ms of pulse communication period
)	Pulses, millimeter (mm), inch (in.)
5 C , error range: -3.5 – +0. 5 C , error range: -1.5 – +1. C , error range: -3 – +1 min	5 min/month 5 min/month /month
·C	
n IEC 61131-2	
ele (compliant with IEC 610	000-4-4)
.5mm; 8.5–150Hz, acceler	ation of 10m/s2; X/Y/Z axis, 10cycles

Digital input module

Model	AX-EM-1600D
Number of channels	16
Input type	Source/sink
Input voltage	DC 24V (up to 30V)
Input current	4.7mA
Port filter time	10ms
Isolation method	Optocoupler
Dimensions (W x H x D)	32x90x117mm

Digital output module

Model	AX-EM-0016DP
Number of channels	16
Output type	PNP transistor (of the source type) output, active high
Power supply voltage	DC24V
Output voltage	12V~24V(-15%~+5%)
Max. load	0.5A/point; 2A/common terminal (resistive load)
Isolation method	Magnetic
Short-circuit protection	Supported (max. current limited to 1.7A when
output	protection enabled)
Dimensions (W x H x D)	32x90x117mm

Digital output module

Model	AX-EM-0016DN
Number of channels	16
Output type	NPN transistor (of the sink type) output, active low
Power supply voltage	DC24V
Output voltage	12V~24V(-15%~+5%)
Max. load	0.5A/point; 2A/common terminal (resistive load)
Isolation method	Magnetic
Short-circuit protection output	Supported (max. current limited to 1.4A when protection enabled)
Dimensions $(W \times H \times D)$	32x90x117mm

Analog input module

Model	AX-EM-4AD
Number of channels	4
Voltage range	±5V, ±10V, +5V, +10V
Current range	0–20mA, 4–20mA, ±20mA
Accuracy in room temperature (of 25°C)	Voltage ± 0.1%; current ± 0.1%
Resolution	24 bits
Disconnection detection	Supported
Limit voltage	± 12V
Limit current	± 24mA
Isolation method	Isolated between I/O port and power supply Not isolated between channels
Dimensions (W x H x D)	32x90x117mm

Communication module

Model	AX-EM-RCM-ET
Communication protocol	EtherCAT
Max. communication rate	100Mbps
Synchronization method	Distributed clocks for the servo; input and output synchronization for I/O
Physical layer	100BASE-TX
Baud rate	100Mbit/s (100BASE-TX)
Transmission distance	Less than 100m between two nodes
Number of slave nodes	1–125. The internal address is automatically allocated according to the network bus connection sequence.
Duplex mode	Full duplex
Topology structure	Linear
Transmission medium	Category-5 or higher twisted pair
Process data	Up to 1486 bytes contained in a single Ethernet frame
Refresh time	The refresh time of 1000 digital inputs and outputs is about 30μ s, and that of 32 servo applications is about 100μ s.
Dimensions (W x H x D)	32x90x95mm

Analog output module

Model	AX-EM-4DA
Number of channels	4
Voltage range	±5V, ±10V, +5V, +10V
Current range	0–20mA, 4–20mA
Accuracy in room temperature (of 25°C)	Voltage ± 0.1%; current ± 0.1%
Resolution	16 bits
Disconnection detection	Supported
Isolation method	Isolated between I/O port and power supply Not isolated between channels
Dimensions $(W \times H \times D)$	32x90x117mm

Temperature module

AX-EM-4PTC
4
Two-, three-, or four-wire
PT100, PT500, PT1000, CU100
Types B, E, J, K, N, R, S, and T
Thermal resistance: Full scale $\pm 0.3\%$ Thermocouple: Full scale $\pm 0.1\% \pm 1\mathrm{C}$
Thermal resistance: Full scale±1% Thermocouple: Full scale ±0.3%±1 C
Internal/external
24 bits
0.1°C/°F
Isolated between I/O port and power supply Not isolated between channels
32x90x117mm

Main Dimensions



Unit: mm

Extension module (Digital/Analog/Temperature)



Unit: mm

Tail-board



Unit: mm



Power supply



Unit: mm

Communication module





Ordering Data

Model	Description
AX70-C-1608P	CPU module; EtherCAT/CANopen/Ethernet, RS485*2, PNP transistor output; RoHS
AX71-C-1608P	CPU module; EtherCAT (8-axis)/CANopen/Ethernet, RS485*2, PNP transistor output; RoHS
AX-PWR	Power supply module; Input 100–240VAC 50Hz/60Hz; Output 2A, 24VDC; RoHS
AX-EM-1600D	Digital input module; 16 inputs, 24VDC, supporting the source and sink types; RoHS
AX-EM-0016DP	Digital output module; 16 PNP transistor outputs, max. current 500mA, 24VDC; RoHS
AX-EM-0016DN	Digital output module; 16 NPN transistor outputs, max. current 500mA, 24VDC; RoHS
AX-EM-4AD	Analog input module; 4 analog inputs, 24-bit resolution, room-temperature accuracy±0.1%; RoHS
AX-EM-4DA	Analog input module; 4 analog inputs, 16-bit resolution, room-temperature accuracy±0.1%; RoHS
AX-EM-RCM-ET	Communication module; EtherCAT slave-node module, supporting the expansion of 16 I/O modules; RoHS
AX-EM-4PTC	Temperature detection module; 4-channel thermal resistor & thermocouple temperature detection module, 24-bit resolution, sensitivity of 0.1 C/ F; RoHS Supported thermocouples: Types B, E, J, K, N, R, S, T Supported thermal resistors: PT100, PT500, PT1000, CU100

Optional parts

Model	Description
AX-HIO-40	Signal processing module; 40-pin high-speed I/O adapter terminal block; RoHS
AX-L1-10	Data cable; High-speed I/O lead cable, L=1m; RoHS
AX-L1-20	Data cable; High-speed I/O lead cable, L=2m; RoHS
AX-L2-10	Data cable; RS485/CAN communication cable (DB9 male), L=1m; RoHS
AX-L2-20	Data cable; RS485/CAN communication cable (DB9 male), L=2m; RoHS
AX-L2-50	Data cable; RS485/CAN communication cable (DB9 male), L=5m; RoHS
AX-L3-20	Data cable; Category-5e shielded network cable, L=2m; RoHS
AX-L3-50	Data cable; Category-5e shielded network cable, L=5m; RoHS

New impetus for modern industrial upgrading >>













Easy to meet complex motion control requirements

The product can help you to easily achieve positioning control, high synchronization control, and cam control by means of simple parameter setting and programming through the integrated high-speed EtherCAT bus and visual programming environment, which meets the real-time, high-speed, high-precision and personalized control needs, suitable for packaging, printing, lithium battery and other industries.

High flexibility control solution to realize distributed control

Forms a diverse and open industrial network, which improves the efficiency of technical personnel and adapts to the changing system expansion and project optimization requirements. Each controller can realize a single controller control solution, or multiple controllers can form a distributed control system, which can be widely used in industries such as multi-color printing and lithium battery.

Large-scale I/O application

Based on the EtherCAT bus, the distributed I/O system ensures the flexibility of data transmission systems and reliability of communication between the controller CPU and I/O. It is applicable to large-scale production lines with multi-process, multi-control points and rapid response application requirements, such as filling, packaging, labeling, and packaging, helping the automation transformation and upgrade of production lines and equipment.

Automation Product Family









■ HMI

VK Series VT Series

Controller

VC Series All-in-one Machine IVC1S Series Programmable Controller IVC1L Series Programmable Controller IVC2L Series Programmable Controller IVC3 Series Programmable Controller AX Series High-performance Programmable Controlle

Servo System

General servo drive System

- Industry specific servo system
- Industry specific electronic control system

Low-voltage general VFD Midum-voltage VFD Industry specific VFD





